# AIFS

ECMWF's data driven forecast model

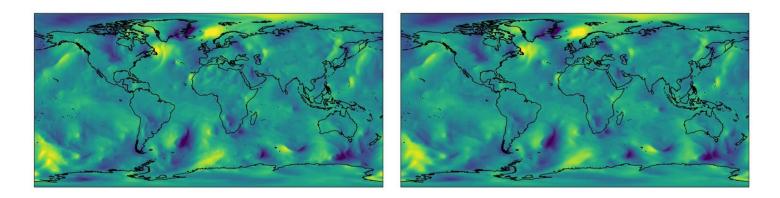
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## **AIFS**

- -> following Keisler 2022 and Lam et. al 2022
- GNN architecture: Interaction Networks (Battaglia et. al 2016)
- Graph representation, hidden multi-scale mesh, edge features



Why GNN : can handle arbitrary input grids, local grid refinement, changing grids etc. ; attractive for use in earth system science

AIFS

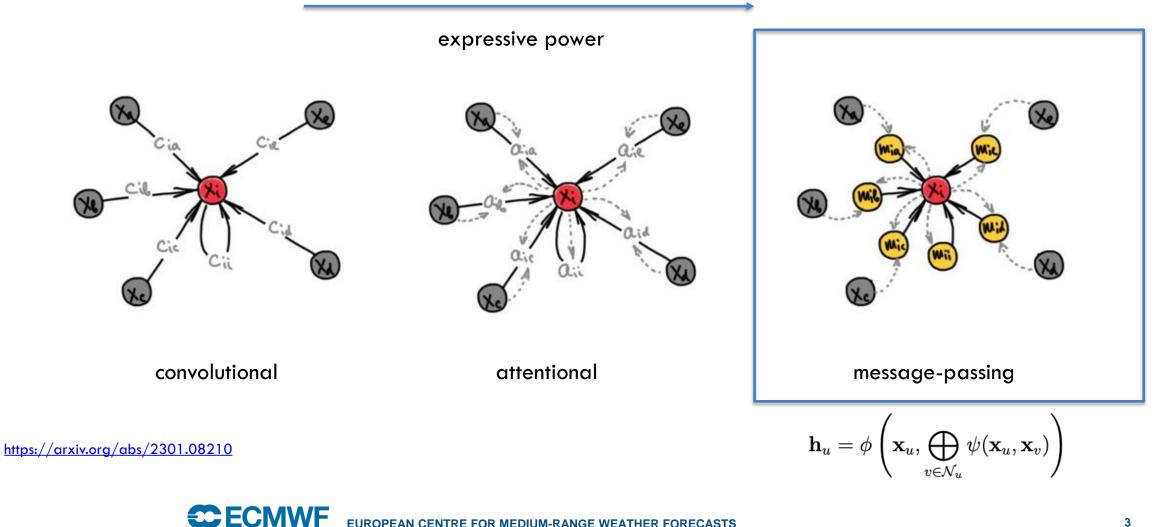
- built from flexible message-passing GNNs



#### Computer Science > Machine Learning

[Submitted on 24 Dec 2022 (v1), last revised 4 Aug 2023 (this version, v2)]

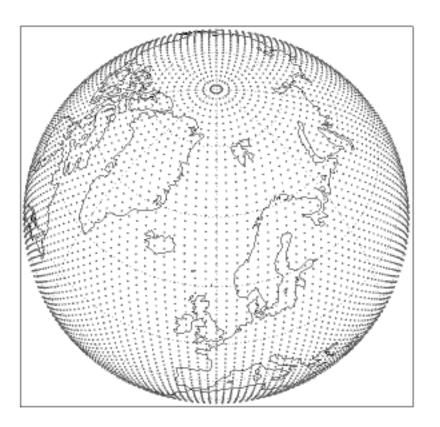
GraphCast: Learning skillful medium-range global weather forecasting



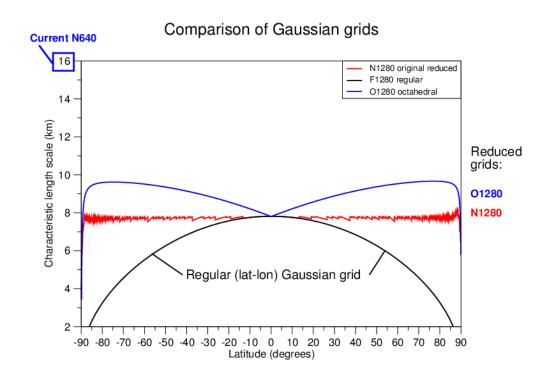
**EUROPEAN CENTRE FOR MEDIUM-RANGE WEATHER FORECASTS** 

https://thegradient.pub/graph-neural-networks-beyond-message-passing-and-weisfeiler-lehman

**AIFS grid** 

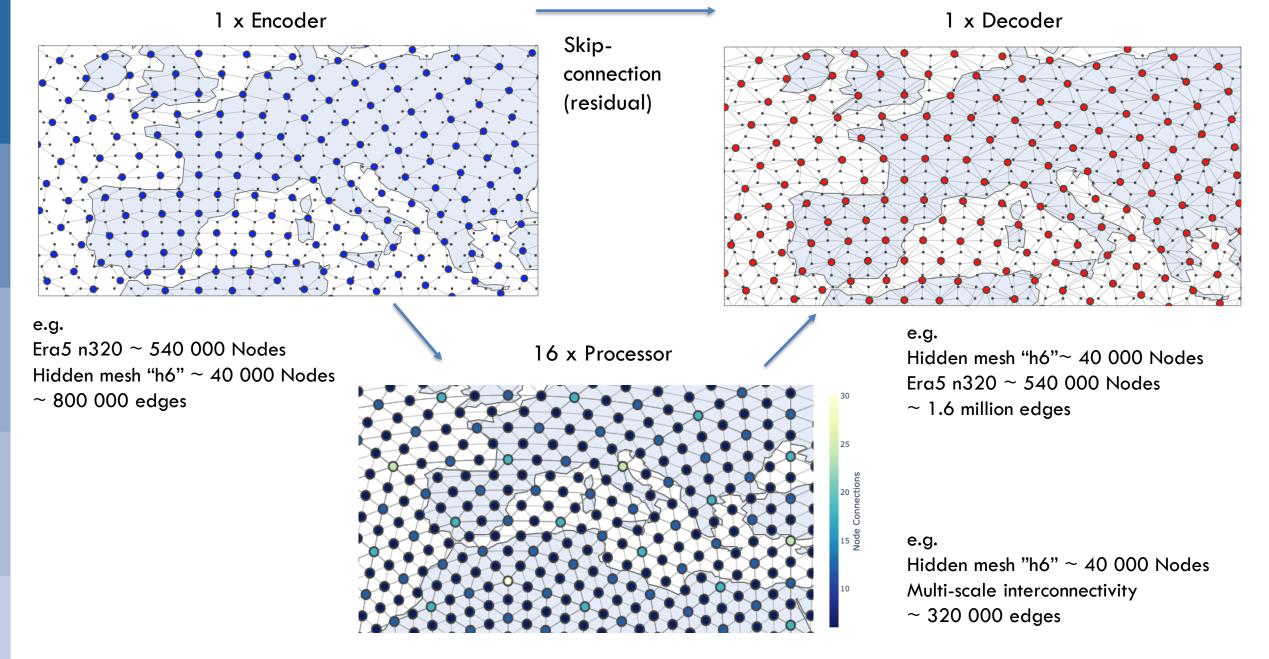


o96 / o160 / n320

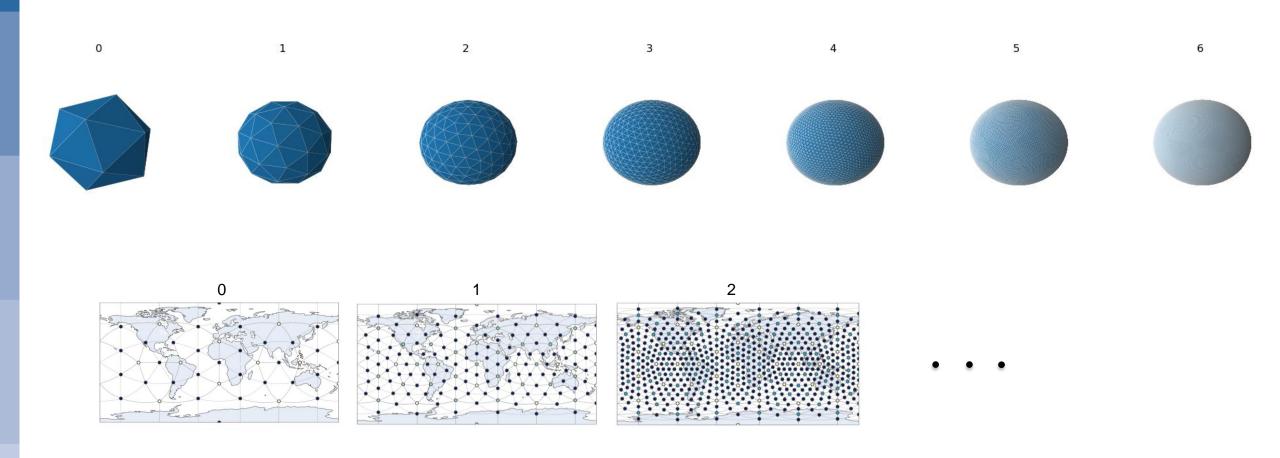


- + (equi-)area weights
- + weighting along plevs (vertical)
- + per-variable weights in the loss

https://confluence.ecmwf.int/display/FCST/Introducing+the+octahedral+reduced+Gaussian+grid

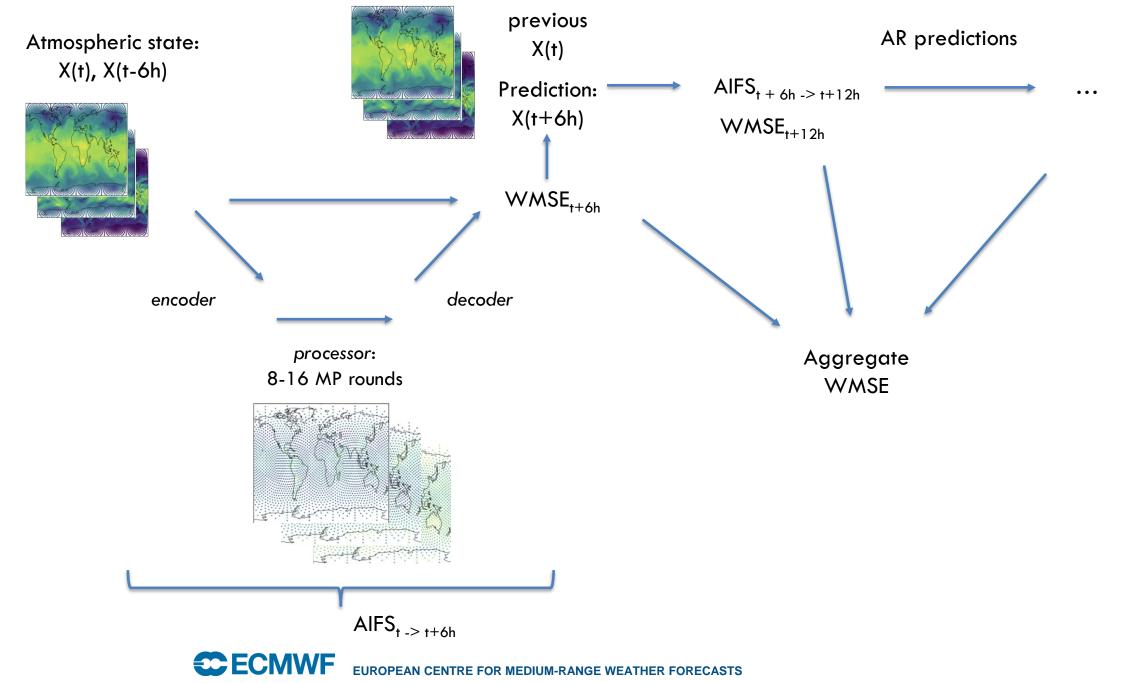


#### Simultaneous multi-level message passing





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#### **AIFS current reference model**

#### Model:

- O96 ERA5 grid, ~1-degree
- "Level 5" hidden grid, ~2-degree
- MLP dimension 768 (cf. 512 for GraphCast)
- 80 million parameters

#### Variables:

13 pressure levels – u, v, w, q, t, z surface: 2t, 10u, 10v, 2d, sp, msl, sst

#### Training:

Step 1: 4 days on 16 GPUs to minimise errors for single 6h step
Step 2: 34 hours on 16 GPUs to minimise errors up to 3 days
Step 3: 4 hours on 16 GPUs minimising errors up to 3 days on operational analysis

#### Total ~6 days on 16 GPUs

### Scaling up AIFS

- Modest number of parameters, model size currently not much of an issue
- Data size is large, lots of grid points -> lots of nodes and edges (similar to very large sequence length in transformer based\* models)

GPU memory is limited => 40 GB on ATOS, 64 GB on LUMI / Leonardo

For large (parameters) models there exist quasi out of the box libraries, this is not the case for big input data.

Memory saving options:

Do not keep everything in memory -> use re-computation in backward : large memory savings. We trade compute for memory as much as possible.

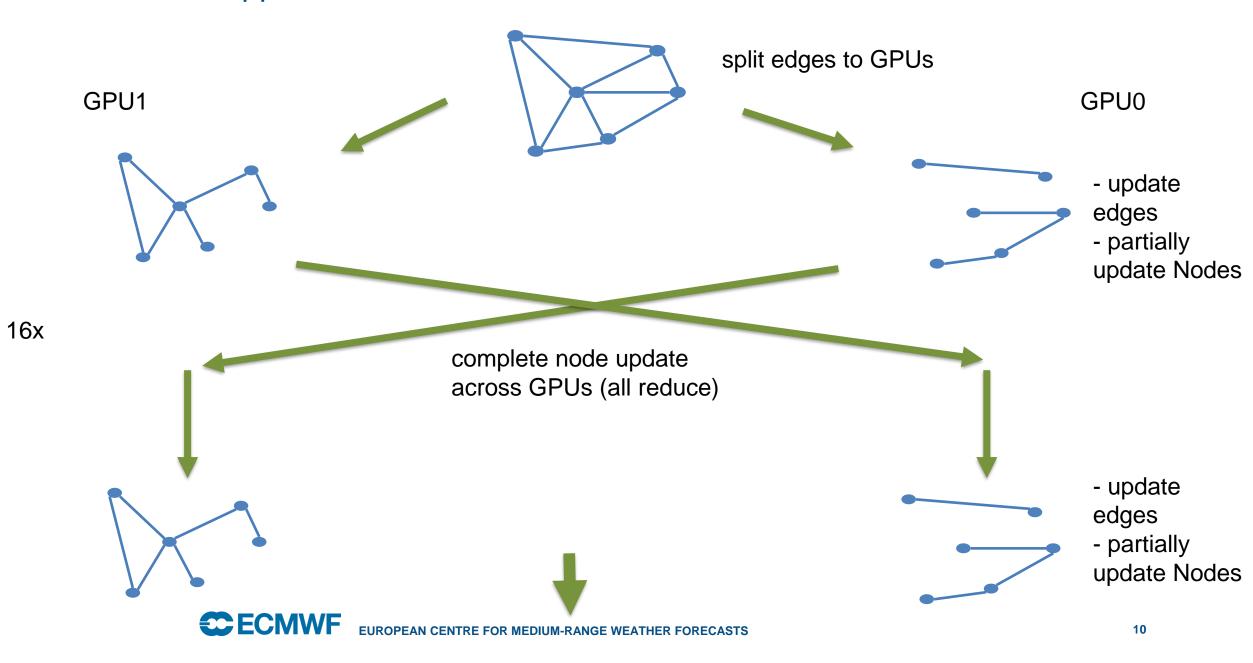
Multi GPU model : shard one model instance across multiple GPUs ; forward and backward pass different in terms of required communication => increases instantaneous available memory for more edges / nodes and also possible to split activations across

=> increases instantaneous available memory for more edges / nodes and also possible to split activations across GPUs

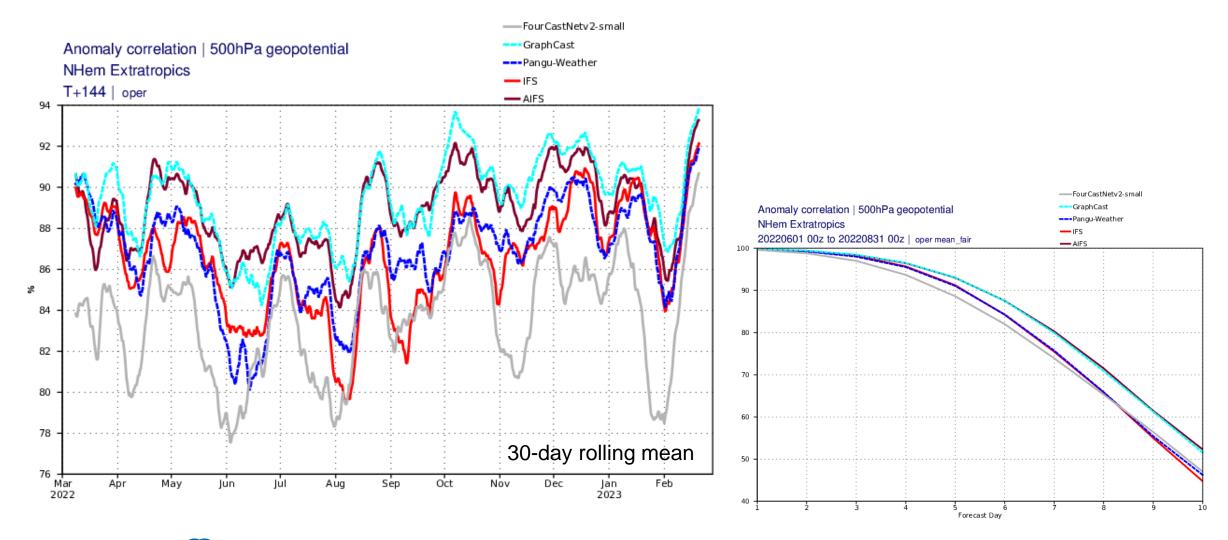
- Aggressive re-computing activations allows for rollouts of ~ 1. degree model on a single GPU
- Model parallel set-up makes it possible to go to native ERA5 resolution (and beyond?) and faster time to solution ; it will also allow to build larger models in the future

Model Parallel approach:

 $edge_new = f(x_0, x_1, edge)$   $x_new = f(x_0, sum(edges_new))$ 



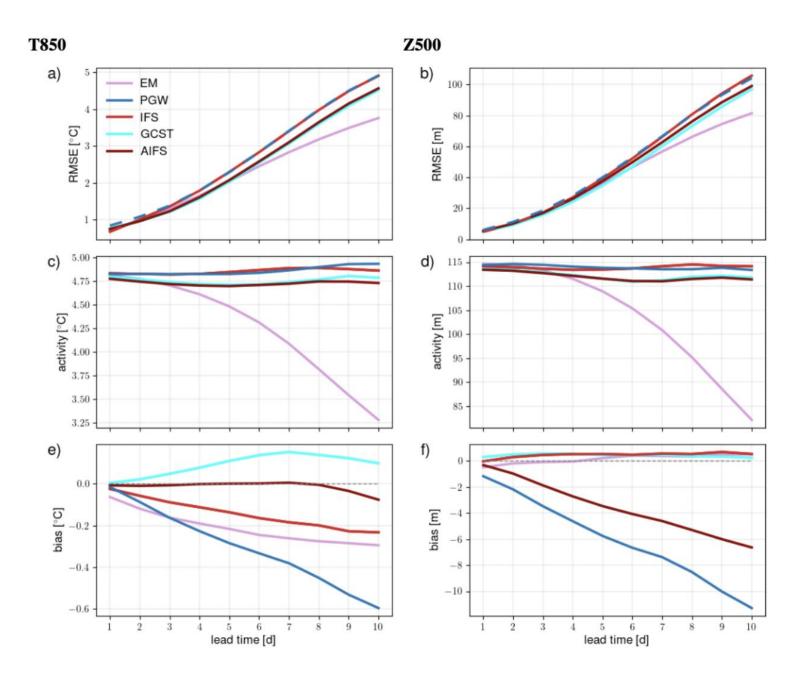
#### Headline score: anomaly correlation for Z500



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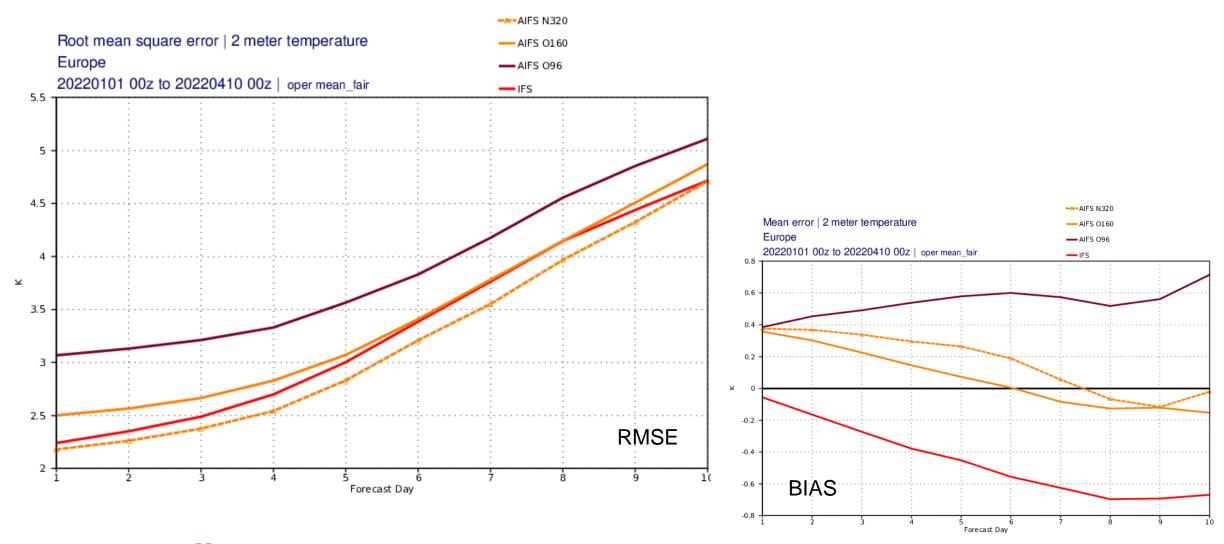
RMSE, activity, and bias

DJF 2022/2023 NHem Extratropics





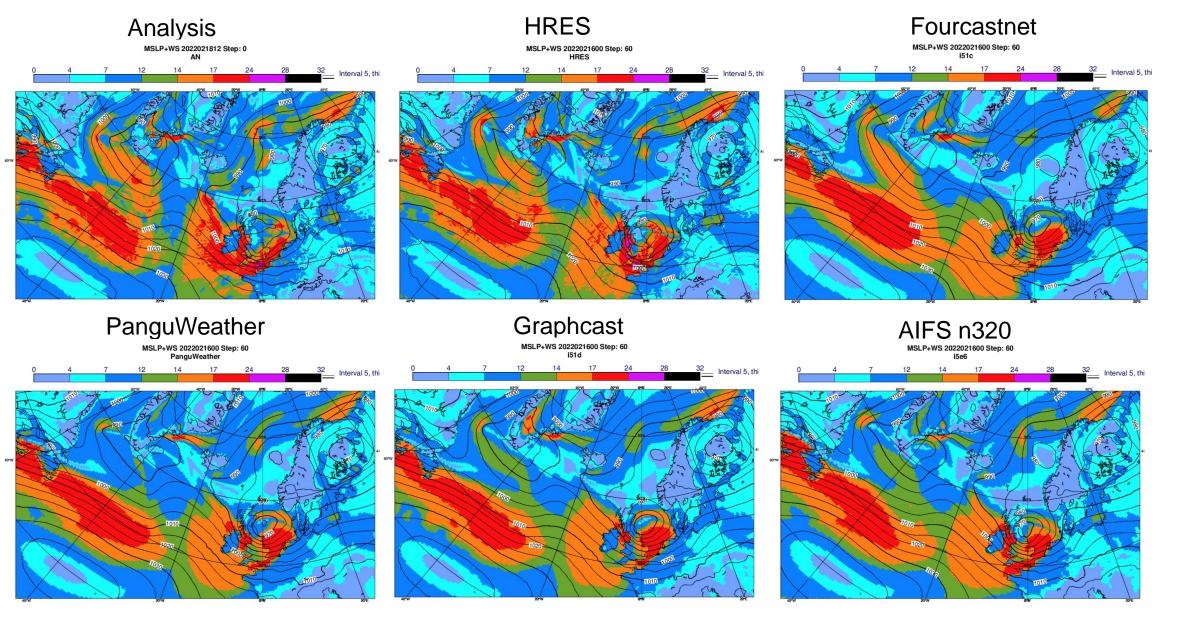
### Verification against SYNOP observations



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### 2022-02-16 00z + 60h (Storm Eunice over UK)

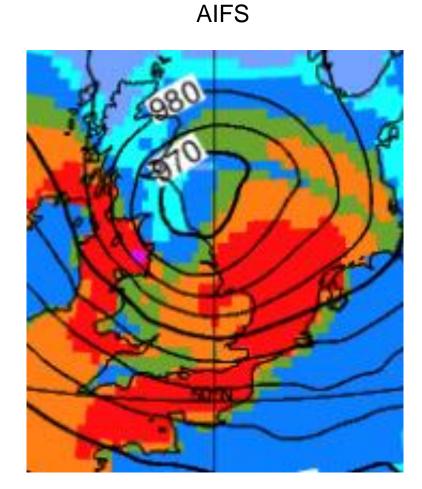
See ECMWF Newsletter 176

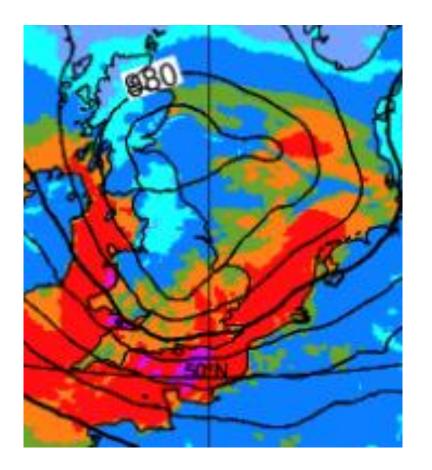




### 2022-02-16 00z + 60h (Storm Eunice over UK)

IFS



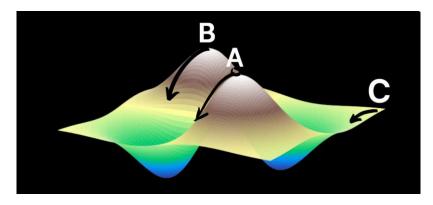


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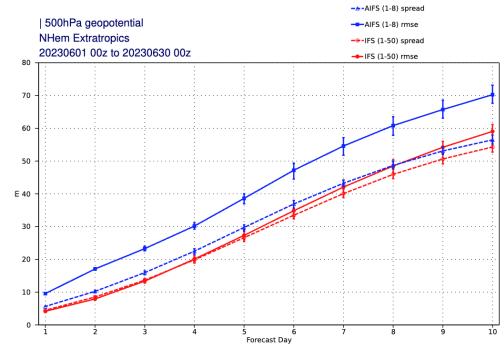
## Towards Ensembles -> Preliminary ideas to capture uncertainty

1. Use the ensemble initial conditions to initialise the AI model

2. Using the randomness of the optimisation process to find different quasi-optimum solutions of the NN weights that can be used to build a *multi-model ensemble* 



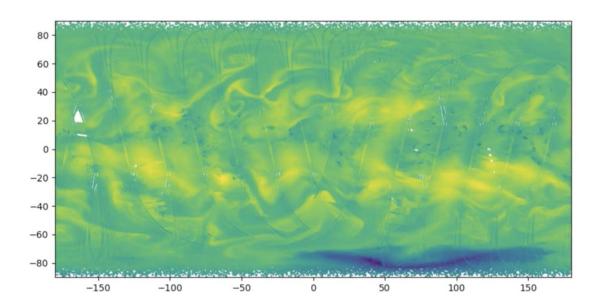
- 3. Train to minimise *probabilistic scores* like kernel CRPS or optimise distributions
- 4. Generative models where NN is trained on real samples and then generates new samples. Examples include Generative Adversarial Networks and Diffusion models

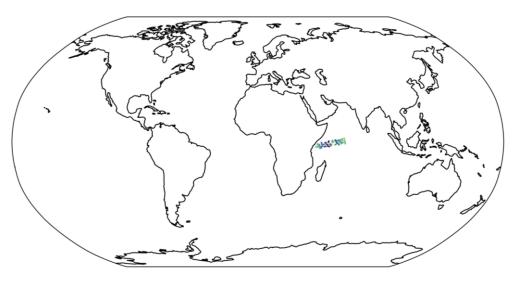


### Learning from observations: challenges

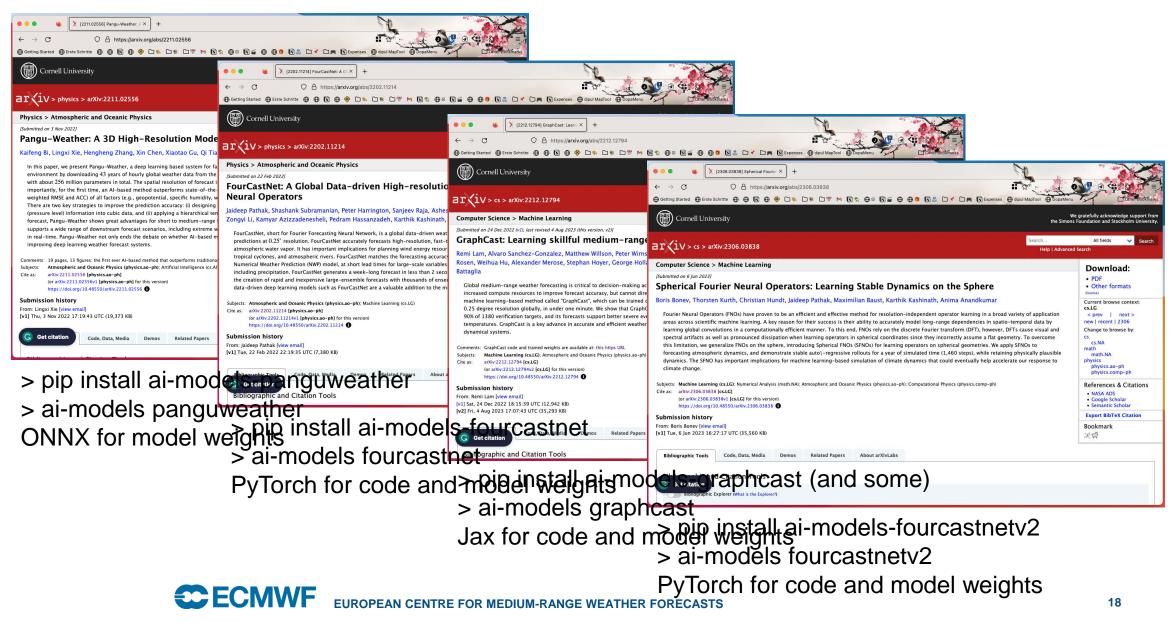
Multitude of scattered and noisy data needs to be fused into coherent representation.

- Data is sparse in space and time
- Heterogeneity of data sources
  - Different vertical levels, ...
  - Many sources need to be combined
- Measured values are not standard physical fields and differ by source
  - Of interest are quantities like T2m, U10m, V10m, ...
  - Observation operators if necessary
- How to handle biases and quality control?





### AI-Models Plugins for FOSS Data-Driven NWP



#### prepml

- prepml is the companion tool to ai-models
- Uses ecFlow
- It allows to run inferences over many years
- Archives all outputs in the MARS archive in research mode
- It feeds into ECMWF's scores database so that models can evaluated
- It allows users to run development code as well
- It can create ensembles using various combinations of models, inputs, ...

#### Summary

- We have an accurate baseline model
- Model can be scaled up to high-resolution
- Extensive supporting software infrastructure
- GNN can support arbitrary grids, including high resolution over only parts of the globe
- Using this basis we can explore
  - Different methods for constructing reliable ensemble forecasts
  - Using observations either with or replacing analysis.



## **Questions?**



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